

SIEMENS



BACnet LCM-OAVS

Room Pressurization with Slow-acting Damper Actuation (One Exhaust, One Supply) and Hot Water Reheat, Application 6753

Application Note

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Overview

Application 6753 controls pressurization, ventilation, and room temperature in a laboratory room served by one single-duct supply terminal with a reheat coil, one general exhaust terminal, and up to six fume hoods (multiple fume hood flow signals must be averaged using an averaging and scaling module. Pressurization is controlled by maintaining a selected difference between supply and exhaust airflows.

This version of the LCM uses conventional supply and exhaust actuation (rather than high speed actuation). Therefore, it should be used only where rapid room response to fume hood volume changes is not required. Fume hoods used in conjunction with these applications should be constant volume or slow actuation.



NOTE:

Application 6753 can be set up to operate without a supply box, or without a general exhaust box. See the *Application Notes* section for more information.

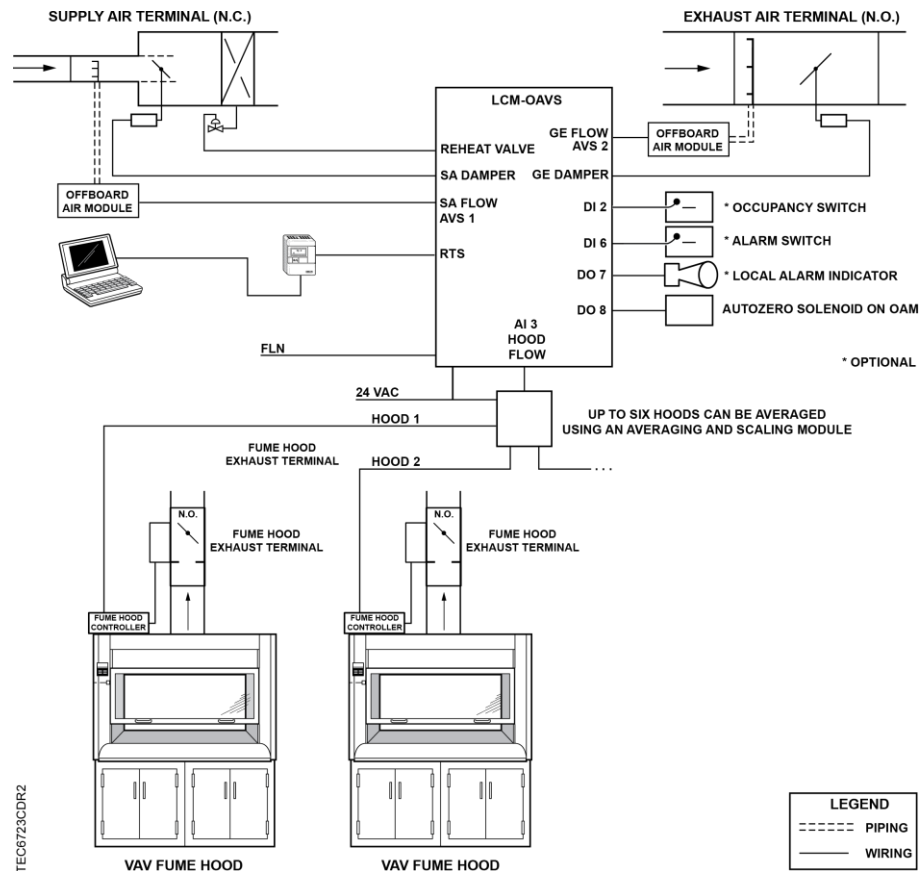


NOTE:

The LCM controls pressure, ventilation, and temperature. When these functions conflict, the priorities are:

- Pressurization
 - Ventilation (supply minimum may be overridden to maintain negative pressurization)
 - Temperature
-

Temperature control is determined by input from the room temperature sensor.



Ventilation and Pressurization Control Drawing.

BACnet

The controller communicates using BACnet MS/TP protocol for open communications on BACnet MS/TP networks.

Product	Supported BIBBs	BIBB Name
BTEC/PTEC	DS-RP-B B	Data Sharing-Read Property-B
	DS-RPM-B	Data Sharing-Read Property Multiple-B
	DS-WP-B	Data Sharing-Write Property-B
	DM-DDB-B	Device Management-Dynamic Device Binding-B
	DM-DOB-B	Device Management-Dynamic Object Binding-B
	DM-DCC-B	Device Management-Device Communication Control-B
	DM-RD-B	Device Management-Reinitialize Device-B
	DM-BR-B	Device Management-Backup and Restore-B
	DM-OCD-B	Device Management-Object Creation and Deletion-B
	CPT	Confirmed Private Transfer (Auto Discovery)
	UPT	Unconfirmed Private Transfer

Auto Discovery

Auto Discovery allows you to automatically discover and identify PTEC/ATEC controllers on the BACnet MS/TP Network. There are two basic configurations:

- Devices not configured with an address. (Devices are discovered by their unique serial number.)
- Devices configured with an address and available for modification.

Auto Addressing

Auto Addressing allows you to automatically assign device addresses to a PTEC/ATEC controller on the BACnet MS/TP Network. If a controller is not configured with a MAC address, you have the option to auto-address or manually address the controller. During this time the baud rate is automatically detected by the controller.

Controller(s) must be connected on the BACnet/IP network in order for automatic addressing to occur.

Hardware Inputs

Analog

- Air velocity sensor (s) – (one or two depending on setup)
- Fume hood controller input or FFM
- Room temperature sensor

Digital

- Occupancy button (option on room temperature sensor)
- *(Optional)* Occupancy switch
- *(Optional)* Alarm switch

Hardware Outputs

Analog

- Reheat valve

Digital

- Autozero Solenoid in Offboard Air Module (DO 8)
- *(Optional)* Alarm
- Supply damper (two DOs)
- General exhaust damper (two DOs)

Ordering Notes

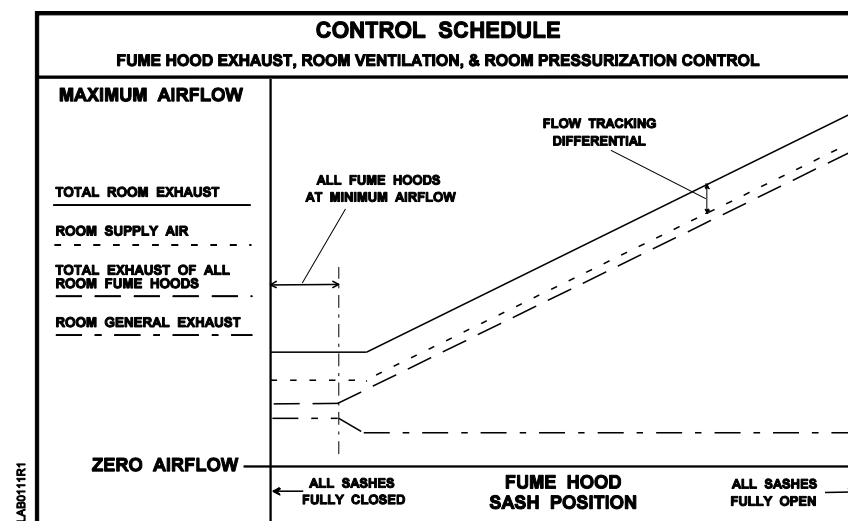
570-801PA	BACnet LCM-OAVS Room Pressurization with Slow-acting Damper Actuation (One Supply, One Exhaust) and Hot Water Reheat Requires Offboard Air Module(s) – order and ship separately
550-819B	Offboard Air Module (OAM) – order and ship separately

Sequence of Operation

The following paragraphs present the sequence of operation for BACnet LCM-OAVS VAV Room Pressurization with HW Reheat and Slow Damper Actuation.

Pressurization Control

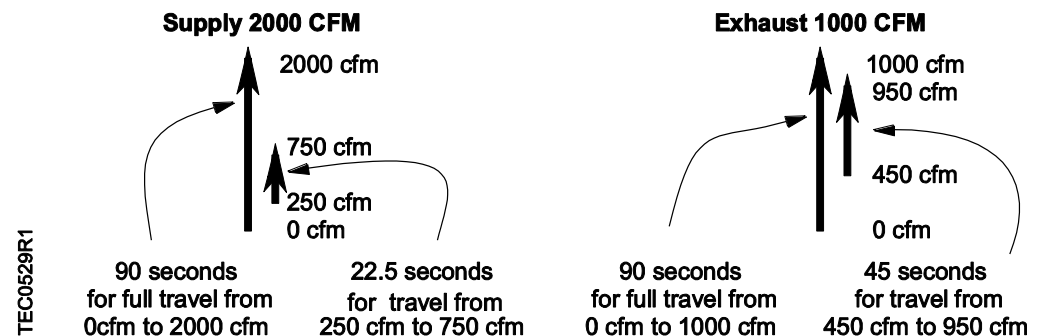
The goal of pressurization control is to maintain a fixed difference between the volumes of total supply air and total exhaust air (see the following figure). The controller selects supply and exhaust setpoints to balance flows while meeting supply air requirements, and the supply and exhaust flows are individually controlled by their respective feedback loops in order to meet the setpoints.



Optional Rate Limiting of Actuators

Under specific circumstances, such as when operating open loop with setpoint tracking and differently sized supply and exhaust, it may be necessary to adjust the actuator travel rates to improve pressurization control.

The example below illustrates when a rate limit might be needed, such as when equal travel times for the supply and exhaust actuators yield large differences in their respective flow rates.



To deal with the possibility of unequal flow rate changes, the application includes two new points which allow field adjustment to slow down actuators. **SUP MAX RATE** effectively limits the speed of the supply actuator; **GEX MAX RATE** effectively limits the speed of the exhaust actuator.

SUP MAX RATE and **GEX MAX RATE** should be changed to values other than 0 only after a thorough analysis has been made of the job specific scenarios. For example, slowing down a given supply actuator to match a general exhaust actuator may actually be detrimental overall if the installation includes faster acting fume hoods.

To limit the rate of the actuator (supply or exhaust depending on your setup) that controls the larger and faster changing flow rate, do the following: Take the max flow cfm value of the box you want to slow down and divide by its actuator runtime in seconds, then divide the result by 4 and round to the nearest integer. Enter this final value in either SUP MAX RATE or GEX MAX RATE depending on which box you want to slow down.

Here is the formula in its simplest terms, where “*max cfm*” represents the maximum flow value of the box that you want to slow down:

$$(\text{max cfm} \div \text{runtime}) \div 4 = \text{SUP (or GEX) MAX RATE}$$

**NOTE:**

This value is a good starting point. If necessary, you can raise it (must be an integer) to speed up the rate of flow change, or lower it to further slow down the rate of flow change, while observing the overall stability of your setup.

To accommodate the largest variety of room configurations and pressurization needs, the rate limit will ONLY be applied when the actuator is moving in the direction that, if left uncontrolled, could cause pressurization reversal. See the following table:

	SUPPLY	GENERAL EXHAUST
OCC DIF STPT (or UOC DIF STPT) <0 Maintain positive pressurization	The SUP MAX RATE is applied to supply closing, but not to supply opening.	The GEX MAX RATE is applied to general exhaust opening, but not to general exhaust closing.
OCC DIF STPT (or UOC DIF STPT) >=0 Maintain negative pressurization	The SUP MAX RATE is applied to supply opening, but not to supply closing.	The GEX MAX RATE is applied to general exhaust closing, but not to general exhaust opening.

Room Airflow Balance

The difference between total supply flow and total exhaust flow is the room airflow balance as shown in these calculations:

$$\begin{aligned}\text{VOL DIFFRNC} &= \text{TOTL EXHAUST} - \text{TOTL SUPPLY} \\ &\text{-or-} \\ \text{VOL DIFFRNC} &= (\text{HOOD VOL} + \text{GEX AIR VOL} + \\ &\quad \text{OTHER EXH}) - (\text{SUP AIR VOL} + \text{OTHER SUP})\end{aligned}$$

The controller uses these calculations to maintain VOL DIFFRNC at the VOL DIF STPT.

**NOTE:**

VOL DIFFRNC and VOL DIF STPT are positive numbers in a room that is negatively pressurized and negative in a positively pressurized room.

Application 6753 has the ability to maintain a different volume differential setpoint during occupied mode than during unoccupied mode. When OCC.UNOCC = OCC, VOL DIF STPT = OCC DIF STPT. When OCC.UNOCC = UNOCC, VOL DIF STPT = UOC DIF STPT.

Occupancy

The controller keeps track of the occupancy status of the room and uses that information for the following purposes:

- To select minimum and maximum flow rates for each air terminal.
- To select whether the controller is operating in the VAV or CV mode.
- To determine whether the controller is using Supply Tracks Exhaust (STE) or Exhaust Tracks Supply (ETS) flow tracking.
- To determine the value of VOL DIF STPT.
- To calculate the airflow level that triggers the ventilation alarm.

Occupancy status also affects the airflow level that triggers the ventilation alarm. The occupancy status of the room is indicated by OCC.UNOCC. A digital room thermostat can read OCC.UNOCC and display its value. This point cannot be overridden.

If the occupancy status of the room is set manually, it is necessary to work through the following command options.

The controller works in the occupied mode whenever **one or more** of the following occupancy signals indicates occupancy:

- Commands from a field panel, NET OCC CMD
- Dry contact switch in the room, OCC SWIT DI2
- Push button on the thermostat, OCC BUTTON

If **all** of these occupancy signals indicate vacancy, the controller works in the unoccupied mode.

NET OCC CMD – The NET OCC CMD may be set from a field panel by OCC and UNOCC commands to the LCTLR point. The commands may come from a time-of-day schedule, a PPCL program, or operator commands. These commands work on the LCTLR without unbundling.

**NOTE:**

The displayed OCC/UNOCC status of the LCTLR point does not always match the occupancy status of the controller. To get an actual indication of occupancy status, OCC.UNOCC must be used.

If network commands are not required and occupancy will be set by sources in the room, set NET OCC CMD to UNOCC. If set to OCC, the controller will stay in occupied mode.

OCC ENA is an analog point whose value determines whether or not OCC BUTN DI1, or OCC SWIT DI2, is enabled.

The following table shows what is enabled when OCC ENA is at a particular value.

OCC ENA Values.	
OCC ENA (value)	Description
0 (default)	Both OCC BUTN DI1 and OCC SWIT DI2 are disabled.
1	Only OCC BUTN DI1 is enabled.
2	Only OCC SWIT DI2 is enabled.



NOTE:

OCC ENA does not allow both OCC BUTN DI1 and OCC SWIT DI2 to be enabled at the same time. If OCC ENA is set greater than 2, it will default to 0.

OCC SWIT DI2 – The occupancy switch (dry contact switch in the room) can be any device that closes the switch when the room is occupied (occupancy sensor, extra contact on light switch, and so on). The controller uses this input for occupancy if the setup point OCC ENA is set to **2**. Otherwise, OCC SWIT DI2 does not affect occupancy.

OCC BUTTON – Some thermostats include a momentary switch with a push button. The controller can use this button as a source of occupancy commands if the setup point, OCC ENA, is set to **1**.

When the room sensor button is pushed, the controller interprets this as a request to change the occupancy status of the room. If the room is unoccupied, it changes to occupied. If it is occupied, it *may* switch to unoccupied, depending on the states of the other occupancy sources. The current request status of the room sensor button is indicated by BUTTON CMD. This point is used to investigate the room sensor button's effect on the occupancy status of a room.

OCC BUTTON does not provide that information because it is connected to a momentary switch.

Active Flow Minimums and Maximums

When OCC.UNOCC equals OCC:

- The active supply airflow minimum equals OCC SUP MIN.
- The active supply airflow maximum equals OCC SUP MAX.
- The active general exhaust airflow minimum equals OCC GEX MIN.
- The active general exhaust airflow maximum equals OCC GEN MAX.

When OCC.UNOCC equals UNOCC:

- The active supply airflow minimum equals UOC SUP MIN.
- The active supply airflow maximum equals UOC SUP MAX.
- The active general exhaust airflow minimum equals UOC GEX MIN.
- The active general exhaust airflow maximum equals UOC GEN MAX.

VAV versus CV Control

In Application 6753, VAV means that the supply airflow can be varied to provide cooling. CV means the supply airflow is not a source of cooling. However, the supply and general exhaust can still change in CV mode to keep the volume differential setpoint constant. This may be necessary if HOOD VOL is varying. Application 6753 can do either Variable Air Volume control (VAV) or Constant Air Volume Control (CV). It can also change the type of air volume control based on which mode it is operating in (OCC or UNOCC).

- When OCC.UNOCC equals **OCC**, Application 6753 will perform VAV control provided that VOLUME STATE equals 1 or 3. It will perform constant volume (CV) control provided that VOLUME STATE equals 0 or 2.
- When OCC.UNOCC equals **UNOCC**, Application 6753 will perform VAV control provided that VOLUME STATE equals 2 or 3. It will perform constant volume control provided that VOLUME STATE equals 0 or 1.

Depending on how VOLUME STATE is configured, Application 6753 can operate as either a Variable Air Volume (VAV) LCM or a constant volume (CV) LCM. Also, these operational modes can vary between the occupied and unoccupied periods, if desired.

The following table shows what the application does when VOLUME STATE is at a particular value.

VOLUME STATE Values.	
VOLUME STATE (value)	Description
0	Always Constant Volume.
1 (default)	VAV during occupancy, Constant Volume during unoccupied period.
2	Constant Volume during occupancy, VAV during unoccupied period.
3	Always VAV.



NOTE:

If VOLUME STATE is set greater than 3, it will default to 0.

Fume Hood Flow Input

A signal of 1 to 10 Vdc at AI 3 represents the volume of air that is exhausted through the fume hood(s). By using a Fume Hood Flow Module (FFM), you can connect up to six fume hoods to AI 3. Multiple fume hood flows must be averaged using a Fume Hood Flow Module. The resulting airflow is displayed in point HOOD VOL.

MAX HOOD VOL is set during start-up to indicate the flow in cubic feet per minute (cfm) that corresponds to an input signal of 10 Vdc. A signal of 1 Vdc indicates 0 cfm. If the signal drops below 1 Vdc, TOTL EXHAUST will fail.

**NOTE:**

If desired, the LCM can be used without any fume hoods attached. In this case, MAX HOOD VOL should be set to 0 cfm to disable the alarming that would occur if the fume hood flow input drops below 1 Vdc.

Flow Tracking – Supply Tracks Exhaust vs. Exhaust Tracks Supply

The Supply Tracks Exhaust (STE) and Exhaust Tracks Supply (ETS) feature is configured by setting TRACK MODE to STE or ETS to help the controller meet the pressurization needs of the controlled space, such as for negative or positive pressure. TRACK METHOD is used to determine what is being tracked – a flow value or a setpoint value. Regardless of the mode (STE or ETS) in which the controller is operating, the application will change the value of TRACK METHOD from STPT to FLOW (that is, from setpoint tracking to flow tracking) if necessary to maintain proper pressurization. This is important in situations where a room may lack sufficient supply or general exhaust capacity. The following paragraphs explain this in greater detail.

Supply Tracks Exhaust mode is useful when trying to maintain negative pressurization. During Supply Tracks Exhaust, the supply air volume "tracks" or follows the exhaust air volume. If the exhaust air is "broken" (for instance, if the general exhaust airflow control device is stuck open or stuck closed), the supply air volume will be adjusted so that VOL DIF STPT is maintained as much as possible. (The supply air volume cannot go lower than zero and the application will not allow it to go higher than OCC SUP MAX during occupied periods, or UOC SUP MAX during unoccupied periods.)

Exhaust Tracks Supply mode is useful when trying to maintain positive pressurization. During Exhaust Tracks Supply, the general exhaust air volume "tracks" or follows the supply air volume. If the supply air is "broken" (for instance, if the supply airflow control device is stuck open or stuck closed), the general exhaust air volume will be adjusted so that VOL DIF STPT is maintained as much as possible. (The general exhaust air volume cannot go lower than zero and the application will not allow it to go higher than OCC GEX MAX during occupied periods, or UOC GEX MAX during unoccupied periods.)

The selected track mode is not affected by occupancy status (OCC or UNOCC), and is set by the value of TRACK MODE.

TRACK MODE Values.	
TRACK MODE (value)	Description
0 default	Always STE (Supply Tracks Exhaust), exhaust only.
1	STE during occupancy, ETS during the unoccupied period.
2	ETS during occupancy, STE during the unoccupied period.
3	Always ETS (Exhaust Tracks Supply), supply only.

**NOTE:**

If TRACK MODE is set greater than 3, it will default to 0.

TRACK METHOD

TRACK METHOD is a point associated with TRACK MODE. TRACK MODE determines which airflow (supply or general exhaust) gets tracked and which airflow does the tracking. TRACK METHOD determines how tracking is accomplished.

- If TRACK MODE is set to ETS and TRACK METHOD is set for FLOW tracking, the general exhaust flow setpoint is calculated according to the measured value, SUP AIR VOL.
- If TRACK METHOD is set for STPT tracking, the general exhaust flow setpoint is calculated according to the supply flow setpoint. However, this module changes over to FLOW tracking mode if the supply cannot reach the setpoint.

This feature prevents the incorrect pressurization of rooms that lack the required supply capacity. The changeover is based on the error of the supply flow loop. If the error is greater than FAIL LIMIT, and stays that way for a time longer than FAIL TIME, then the module changes from STPT tracking to FLOW tracking. It stays in that mode until the error comes back to zero, then switches back to the STPT tracking mode.

- If TRACK MODE is set to STE and TRACK METHOD is set for FLOW tracking, the supply flow setpoint is calculated according to the measured value, GEX AIR VOL.
- If TRACK METHOD is set for STPT tracking, the supply flow setpoint is calculated according to the general exhaust flow setpoint. However, this module changes over to FLOW tracking mode if the general exhaust cannot reach the setpoint.

This feature prevents the incorrect pressurization of rooms that lack the required general exhaust capacity. The changeover is based on the error of the general exhaust flow loop. If the error is greater than FAIL LIMIT, and stays that way for a time longer than FAIL TIME, then the module changes from STPT tracking to FLOW tracking. It stays in that mode until the error comes back to zero, then switches back to the STPT tracking mode.

Calculating Exhaust Flow Setpoint

When **Supply Tracks Exhaust** (STE) flow tracking is used, the general exhaust airflow setpoint is calculated as follows:

- During VAV operation, the controller calculates GEX FLO STPT by looking at the value of TEMP CTL VOL and determining the general exhaust flow needed to pressurize the room. If TEMP CTL VOL is less than the active supply minimum, the controller ignores TEMP CTL VOL and calculates GEX FLO STPT based on the value of the active supply flow minimum.
- During CV operation, the controller ignores TEMP CTL VOL. Instead, it calculates GEX FLO STPT based on the value of the active supply flow minimum and the amount of general exhaust airflow needed to pressurize the room.

**NOTE:**

When Supply Tracks Exhaust (STE) flow tracking is being used, the controller does not allow GEX FLO STPT (or the actual general exhaust flow) to rise above the active general exhaust airflow maximum. **However, the general exhaust airflow minimum can be overridden in situations where doing so is necessary to maintain desired room pressurization.**

When **Exhaust Tracks Supply (ETS)** flow tracking is used, the general exhaust airflow setpoint is calculated the same during both VAV and CV operation, as follows:

To calculate GEX FLO STPT, the controller determines the general exhaust airflow value that pressurizes the room based on the values of VOL DIF STPT, OTHER EXH, OTHER SUP and either SUP FLO STPT or SUP AIR VOL depending on the value of TRACK METHOD. GEX FLO STPT may not exceed the active general exhaust airflow maximum, but the currently active general exhaust airflow minimum (OCC GEX MIN or UOC GEX MIN) will be overridden if necessary to maintain the desired room pressurization.

Calculating Supply Flow Setpoint

When **Supply Tracks Exhaust (STE)** flow tracking is used, the supply airflow setpoint is calculated the same during both VAV and CV operation, as follows:

To calculate SUP FLO STPT, the controller determines the supply flow value that pressurizes the room based on the values of VOL DIF STPT, OTHER EXH, OTHER SUP, and either GEX FLO STPT or GEX AIR VOL depending on the value of TRACK METHOD. SUP FLO STPT may not exceed the currently active supply airflow maximum.

When **Exhaust Tracks Supply (ETS)** flow tracking is used, the supply airflow setpoint is calculated as follows:

- During VAV operation, the controller calculates SUP FLO STPT by looking at the value of TEMP CTL VOL and determining the supply flow needed to pressurize the room. If TEMP CTL VOL is less than the active supply minimum, the controller ignores TEMP CTL VOL and calculates SUP FLO STPT based on the value of the active supply flow minimum.
- During CV operation, the controller ignores TEMP CTL VOL. Instead, it calculates SUP FLO STPT based on the value of the active supply flow minimum and the amount of supply airflow needed to pressurize the room.



NOTE:

Regardless of the flow tracking method (STE or ETS) being used, the controller does not let the actual supply airflow rise above the currently active supply airflow maximum. **However, the currently active supply airflow minimum (OCC SUP MIN or UOC SUP MIN) will be overridden if necessary to achieve desired pressurization.**

External Flow Values

Airflows not connected to the controller must be taken into consideration when pressurizing the room, including snorkels, canopies, as well as other supplies, such as offices within the lab space controlled by constant volume controllers. Since these inputs are not connected to the controller, the combination of their values must be entered into OTHER SUP and OTHER EXH so the controller can properly control the lab space.



NOTE:

If these airflow values change slowly or predictably (for example, VAV temperature control and/or occ/unoc differences), steps can be taken using PPCL to have the changes sent over the network to update OTHER EXH and OTHER SUP with the new values

Ventilation – VAV Mode

During VAV operation, the ventilation works as follows:

OCC SUP MIN, the occupied supply minimum, is used to ensure that the room receives enough supply air for proper ventilation during the occupied mode. UOC SUP MIN is used to ensure that the room receives enough supply air for proper ventilation during the unoccupied mode. If necessary, the application raises the general exhaust flow to keep the supply flow from dropping below the minimum. See *Calculating Exhaust Flow Setpoint* for more information.



NOTE:

Since Application 6753 places a higher priority on pressurization than it does on ventilation, the currently active supply minimum (OCC SUP MIN or UNOCC SUP MIN) may be overridden to maintain negative pressurization.

Ventilation Setback in VAV Mode

Ventilation setback allows the minimum and maximum flows (air change rate) for each VAV terminal to vary based on occupancy mode (OCC.UNOCC). This allows several options for reducing the ventilation for unoccupied periods, including:

- Lowering the minimum supply flow, which allows a lower air change rate, but maintains cooling control.
- Lowering the maximum flow, which limits the air change rate and reduces cooling capacity.
- Closing the general exhaust, which lowers airflow and disables cooling completely.

Ventilation – Constant Volume Mode

During Constant Volume (CV) operation, the active supply airflow minimum is used to ensure that the room always receives enough supply air for proper ventilation. If necessary, the application raises the general exhaust flow to keep the supply flow from dropping below the minimum. See *Calculating Exhaust Flow Setpoint* for more information.

In CV mode the active supply minimum is the setpoint. The active supply airflow minimum is used to ensure that the room always receives enough supply air for proper ventilation.

During CV operation, the air volume out of the supply box will equal the active supply airflow minimum as long as this is sufficient to maintain proper room pressurization.



NOTE:

Regardless of the operation—VAV or CV temperature control—airflow out of both the supply and general exhaust box will vary as needed in order to maintain proper room pressurization whenever HOOD VOL changes.

AVS Calibration

Calibration of the air velocity transducer(s) is periodically required to maintain accurate air velocity readings. Depending on the value of CAL SETUP, calibration takes place either at fixed time intervals or whenever the application goes into unoccupied mode.

When calibration is in progress, CAL AIR equals YES. After calibration, CAL AIR returns to NO.

The application uses Autozero Modules connected to AUTOZERO DO8. This means that the supply and general exhaust flow control devices do not close during calibration of the transducers.

**NOTE:**

The LCM does not monitor Fume Hood flow changes for 3 seconds during AVS calibration.

Airflow Control

Both supply flow and general-exhaust flow are controlled with a feedback loop to operate the floating control damper motor (either supply or general-exhaust) so that the measured air velocity is maintained at setpoint. To enhance stable flow control, an advanced algorithm is used to calculate a controllable setpoint as the value approaches zero cfm (lps). This feedback loops works as follows:

When the flow is slightly below the setpoint, the LCM opens the floating control damper motor slowly, more and more until the airflow reaches the setpoint, at which time the air damper's position remains constant. If the flow is far below the setpoint, the LCM opens the floating control damper rapidly, more and more until the airflow reaches the setpoint, at which time the air damper's position remains constant. The feedback gains SUP P GAIN and GEX P GAIN are adjusted to tune the flow loops. The sample loop time for the flow loops is fixed at 2.0 seconds. I and D gain are inherent in the system and do not need adjustment.

The application contains logic that prevents the feedback loops from trying to move the damper motors faster than they can actually go. This helps minimize airflow overshoots and undershoots whenever there is a large airflow setpoint change. The greatest amount of position change that the supply damper motor will be allowed to undergo during each execution of the supply airflow feedback loop is $+(100\% * \text{flow loop execution speed}) / \text{MTR1 TIMING}$. Likewise, the greatest amount of position change that the general damper motor will be allowed to undergo during each execution of the general airflow feedback loop is $+(100\% * \text{flow loop execution speed}) / \text{MTR2 TIMING}$. The flow loop execution speed is fixed in this application at 2.0 seconds.

**NOTES:**

1. Open the door to the controlled space or set VOL DIF STPT to zero while the flow loops are being tuned.
2. The floating control damper motor command points are SUP DMP CMD and GEX DMP CMD. Each floating control damper motor may be set up for normally open or normally closed operation depending on the value of MTR SETUP. See the *Damper Configuration section of the Start-up document* for more information on motor setup.

Floating Control Actuation Auto-correct

Floating Control Actuation Auto-correct

In addition to the existing options for floating control actuator full stroke actions, all floating control actuators are provided with additional logic to fully drive open or closed when commanded to 100% or 0%.

Operating Without a Supply or Exhaust

It is possible to run this application without the supply or exhaust if the corresponding flow coefficient is set to zero. When the flow coefficient is zero and the offboard air module is not connected the air velocity sensor will not display a FAIL status and the flow loop will be allowed to run with a flow value of zero. See the *Application Notes* section for more information.

Heating Safety



NOTE:

As a safety feature, these applications include MODHTG FLO to ensure that adequate airflow is present before heating coils are energized. When the supply airflow (in fpm as derived from the supply air velocity sensor) is greater than MODHTG FLO, then the internal point "ok_to_mod" is set to Yes and the modulating heating device is allowed to modulate.

The default value is 300, which means that the airflow over the heating coil must be at least 300 fpm.

Since $CFM = FPM \times Duct\ Area \times Flow\ Coefficient$, the default value of 300 fpm equates to the following cfm:

In a 12-inch diameter duct and a typical flow coefficient of .7, 300 fpm equates to 158 cfm.

$$12\text{ inch diameter} = .75\text{ sq ft} \quad .75\text{ sq ft} \times 300\text{ fpm} \times .7 = 158\text{ cfm}$$

In an 8-inch diameter duct and a typical flow coefficient of .7, 300 fpm equates to 74 cfm.

$$8\text{ inch diameter} = .35\text{ sq ft} \quad .35\text{ sq ft} \times 300\text{ fpm} \times .7 = 74\text{ cfm}$$

If the application uses hot water heat rather than electric heat, then MODHTG FLO may be set lower than the default value of 300. This allows reheating to occur even if the box is operating below its designated minimum flow setting.

In the open loop mode, the measured airflow is always 0. To re-enable heating, the MODHTG FLO value must be set to 0. When used with an electric reheat, the 0 should be set only after a thorough safety review that shows the electric heating mechanism has sufficient internal safeguards (that is, resettable shutoffs) that would operate if the system actually did have insufficient flow.

Using fpm flow rather than cfm makes the feature less dependent on duct size.

There is hysteresis (deadband) around the flow threshold. The heating turns off below a flow of MODHTG FLO, and does not turn back on until the measured flow rises to a level of 50 fpm more than MODHTG FLO. Between MODHTG FLO and MODHTG FLO + 50, the internal point "ok_to_mod" will not change value.

Room Temperature and Setpoint

The application uses the CTL STPT as the setpoint for the Room Temperature PID Loop. When CTL STPT is not overridden and not being controlled by a field panel, then ROOM STPT and CTL STPT are related to each other as follows:

- If ROOM STPT is greater than RM STPT MAX, then CTL STPT is set equal to RM STPT MAX.

- If ROOM STPT is less than RM STPT MIN, then CTL STPT is set equal to RM STPT MIN.
- If ROOM STPT is less than or equal to RM STPT MAX and greater than or equal to RM STPT MIN, then CTL STPT is set equal to ROOM STPT.

If CTL STPT is overridden or being controlled by a field panel, then RM STPT MIN and/or RM STPT MAX have no effect on CTL STPT.

The application also uses CTL TEMP as the temperature input for the Room Temperature PID Loop. When CTL TEMP is not overridden, then:

$$\text{CTL TEMP} = \text{ROOM TEMP} + \text{TEMP OFFSET}.$$

Room Temperature Offset



NOTE:

The Room Temperature Offset feature is optional.

TEMP OFFSET is a user-adjustable offset that will compensate for deviations between the value of ROOM TEMP and the actual room temperature. This corrected value is displayed in CTL TEMP.

$$\text{CTL TEMP} = \text{ROOM TEMP} + \text{TEMP OFFSET}$$

Example

If the actual room temperature is 72.0°F, and the value of ROOM TEMP is 73.0°F, then the value entered into TEMP OFFSET is -1.0. In this case, the value of ROOM TEMP would read 73.0°F, but the value of CTL TEMP would read 72.0°F.

Room Unit Identification

- For Analog Room Units (Series 1000) – The revision number is visually identified by its case.
- For Digital Room Units (Series 200/2300 Firmware Revision 25 or earlier) – The revision number displays for 5 seconds when the room unit is first powered up. These room units will display `laptop` when a laptop is connected and will no longer update room temperature sensor values.
- For Digital Room Units (Series 2200/2300 Firmware Revision 26 and later) – The revision number displays for 5 seconds when the room unit is first powered up or when a laptop is disconnected. These room units will continue to display and update the room temperature sensor values when a laptop is connected.

Room Unit Operation

Sensor Select

SENSOR SEL is a configurable, enumerated point (values are additive). This point tells the controller what type of room unit is being used and how to handle loss of communication, for more information see Fail Mode Operation [→ 27]. It also provides the ability to enable the optional RH and CO2 sensors and indicates which thermistor type is connected.

Room Temperature, Setpoint, RH and CO2

- When the digital room unit (Series 2200/2300) is used, SENSOR SEL selects the source for temperature and setpoint and enables a loss of communications indication:
 - 1 = enables supervision (from the room unit) for fail communications for temperature and setpoint.
 - 2 = enables supervision (from the room unit) for fail communications for relative humidity.
 - 4 = enables supervision (from the room unit) for fail communications for CO2.
- When the analog room unit (Series 1000/2000) is used, SENSOR SEL values for temperature/setpoint, relative humidity and CO2 should be left at their default values (0).

Thermistor Inputs

- Default for input is 10K.
- To enable 100K Ω thermistor on input, see the following table for additive values.

SENSOR SEL Value *	Description
0	Analog Room Unit, 10K
1	Select Digital Room Unit (for temperature sensing and setpoint dial), 10K
2	Relative Humidity (RH) sensing, 10K
3	Digital Room Unit, RH, 10K
4	CO ₂ sensing, 10K
5	Digital Room Unit, CO ₂ , 10K
7	Digital Room Unit, RH, CO ₂ , 10K
8	Analog Room Unit, 100K
9	Digital Room Unit, 100K
11	Digital Room Unit, RH, 100K
13	Digital Room Unit, CO ₂ , 100K
15	Digital Room Unit, RH, CO ₂ , 100k
16	(Not used)

Example 1: Digital Room Unit with temperature, RH, CO2 and 10K thermistor.
 $1+2+4+0 = 7$

Example 2: Analog Room unit with 100K thermistor. $0+0+0+8 = 8$

Room CO2

RM CO2 displays the CO₂ value in units of parts-per-million (PPM). RM CO2 (from the digital 2200/2300 room units) can be used with PPCL in the PTEC/ATEC controller or unbundled for control or monitoring purposes.

Room RH

RM RH displays the relative humidity value in percent. RM RH can be used for PPCL in the PTEC or unbundled for control or monitoring purposes.

RM RH displays the relative humidity value in percent.

PPCL STATUS

PPCL STATUS displays LOADED or EMPTY.

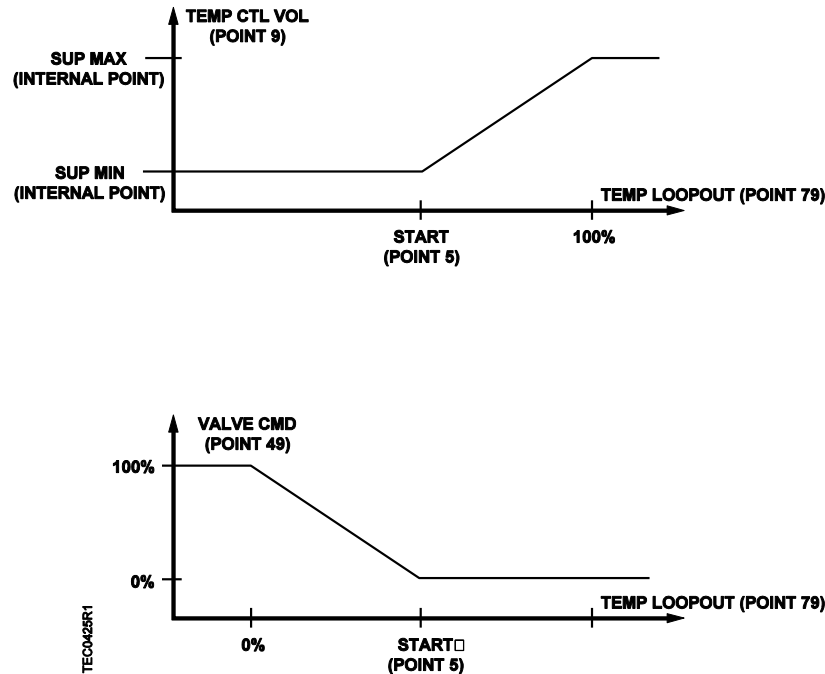
- LOADED = PPCL - programming is present in the controller. A new application number must be assigned (12000 through 12999).
- EMPTY = NO PPCL - programming is present.

The maximum number of PPCL dynamic points is 15.

Temperature Control Loop

Whenever the controller is in VAV control mode, the temperature control portion of Application 6753 works as follows:

The controller adjusts the supply airflow and the reheat valve as necessary to maintain CTL TEMP at CTL STPT. (When neither CTL TEMP nor CTL STPT is overridden, this means the controller tries to maintain ROOM TEMP at ROOM STPT.) The temperature control loop calculates the value of TEMP LOOPOUT. This value is used to sequence the cooling flow and the heating valve. See the following figure. The loop is tuned by adjusting the values of the feedback gains (ROOM P GAIN and ROOM I GAIN and the sample interval, LOOP TIME).



Temperature Control Sequence.

The range of TEMP LOOPOUT is 0 to 100%. Higher values indicate a need for more cooling (or less heat). The Figure *Temperature Control Sequence* shows that as the value of TEMP LOOPOUT moves from START to 0%, and the reheat VALVE CMD is modulated from 0 to 100%. VALVE CMD is converted to a voltage and put out on REHEAT A01. The setup points, VALVE CLOSED and VALVE OPEN, tell the controller the voltage range the valve needs to reach at each end of its stroke.

The controller modulates the cooling flow in sequence with the valve. In this application, temperature control is not the only factor affecting the supply airflow—room pressurization has a higher priority. Therefore, the temperature control sequence does not calculate the supply flow setpoint. Instead, it calculates the amount of supply airflow needed for cooling (TEMP CTL VOL). If this value is compatible with correct room pressurization, it is used as the supply flow setpoint. If not, the actual setpoint, SUP FLO STPT, may be higher or lower than TEMP CTL VOL. As the value of TEMP LOOPOUT moves from START to 100%, TEMP CTL VOL is modulated from the supply minimum to the supply maximum. (During the occupied period, the supply minimum is OCC SUP MIN and the supply maximum is OCC SUP MAX. During the unoccupied period, the supply minimum is UOC SUP MIN and the supply maximum is UOC SUP MAX.

The temperature sequencing point, START, determines what part of the operating range is used for cooling and reheat. By default, it is set to allow 50% of the range to cooling and 50% to reheat. You can alter that balance so it matches the heating and cooling capacities of the equipment. For instance, if the reheat valve has three times the effect of the cooling flow, then setting START to 75% gives an approximately uniform thermal affect across the range of TEMP LOOPOUT. In some cases, this makes it easier to tune the PID loop.

When the controller is operating in the constant volume mode, TEMP LOOPOUT is not allowed to get numerically bigger than the value of START. This means that the application will control the temperature only by modulating the reheat valve; it will make no attempt to control temperature by varying the airflow in the space. During constant volume control, TEMP CTL VOL will remain equal to zero.

Alarms

The controller is equipped with ventilation and pressurization alarms. It does not contain temperature alarms. The controller's alarms are designed to:

- Inform room occupants of hazards.
- Inform building operation personnel that the system is not functioning correctly.
- Supply data for documenting laboratory safety records through trending.

These alarms can be annunciated locally and/or broadcast across a network.

Ventilation Alarm

The alarm level depends on whether the room is occupied or vacant. When the OCC.UNOCC point indicates occupancy, the OC V ALM LVL is used. When the OCC.UNOCC point indicates vacancy, the UC V ALM LVL is used.



NOTE:

In the following discussion, the currently active supply flow minimum is OCC SUP MIN during occupancy and UOC SUP MIN during the unoccupied period. Likewise, the currently active general exhaust box minimum is OCC GEX MIN during occupancy and UOC GEX MIN during the unoccupied period.

The ventilation alarm, VENT ALM, indicates that there is something wrong with the ventilation to the room. VENT ALM has an adjustable alarm level that can vary with the occupancy status of the room. An adjustable delay timer, VENT ALM DEL, prevents nuisance alarms.

VENT ALM is turned on when at least one of the following conditions is true:

- The supply flow to the room, TOTL SUPPLY, stays below the alarm level, for a time at least equal to VENT ALM DEL.
- SUP AIR VOL stays below the currently active supply minimum, for a time at least equal to VENT ALM DEL.
- GEX AIR VOL stays below the currently active general exhaust box minimum, for a time at least equal to VENT ALM DEL.

It is turned off only when all of the following conditions are true:

- The TOTL SUPPLY stays above the alarm level, for a time at least equal to the alarm delay.
- SUP AIR VOL stays above the currently active supply minimum, for a time at least equal to VENT ALM DEL.
- GEX AIR VOL stays above the currently active general exhaust box minimum, for a time at least equal to VENT ALM DEL.

If the current conditions will neither turn on the ventilation alarm nor shut off the alarm, then VENT ALM will keep its current value.

Setting the alarm level to zero means the ventilation alarm will not turn on just because of a low value for TOTL SUPPLY.

Even if the alarm level is set to zero, the ventilation alarm will still turn on if:

- SUP AIR VOL stays below the currently active supply minimum, for a time at least equal to VENT ALM DEL.

and/or

- GEX AIR VOL stays below the currently active general exhaust box minimum, for a time at least equal to VENT ALM DEL.

Pressurization Alarm

The pressurization alarm, VOL DIF ALM indicates that the difference between supply and exhaust flow is not what it should be, or that the controller can't calculate the flow difference, VOL DIFFRNC, because it has lost a flow signal. The Figure *Failure Mode Sequence* lists reasons why VOL DIFFRNC may fail.

The pressurization alarm point is turned on when at least one of the following conditions occurs:

- VOL DIFFRNC has a status of Failed.
- VOL DIFFRNC stays below VOL DIF STPT – DIF ALM DBD for a time at least equal to DIF ALM DEL.
- VOL DIFFRNC stays above VOL DIF STPT + DIF ALM DBD for a time at least equal to DIF ALM DEL.



⚠ WARNING

To ensure that VOL DIF ALM turns on before the pressure in the room changes sign, DIF ALM DBD must be less than the absolute value of VOL DIF STPT.

For example, if negative pressure is desired and VOL DIF STPT equals 70 cfm and DIF ALM DBD is 200 cfm, then the room could go positive by almost 130 cfm without the pressure alarm turning on. In this case, if you want the alarm to turn on before the room changes sign, then you must set DIF ALM DBD to be less than 70 cfm.

The pressurization alarm point is turned off when all of the following conditions occur:

- VOL DIFFRNC has a status of Normal.
- VOL DIFFRNC stays above VOL DIF STPT – DIF ALM DBD for a time at least equal to DIF ALM DEL.
- VOL DIFFRNC stays below VOL DIF STPT + DIF ALM DBD, for a time at least equal to DIF ALM DEL.
- DIF ALM DBD and DIF ALM DEL can be configured to prevent nuisance alarms.

Local Annunciation

ALARM ENA is an analog point whose value determines whether or not a particular alarm activates ALARM DO7.

For ALARM ENA, the terms enabled and not enabled do not mean that a particular alarm is enabled or not. It means whether or not a particular alarm will or will not activate ALARM DO7. For example, if ALARM ENA is set to **1** (Vent Alarm Enabled) and a ventilation alarm occurs, then both VENT ALM and ALARM DO7 will turn on. However, if ALARM ENA is not Vent Alarm Enabled and a ventilation alarm occurs, VENT ALM will turn on, but ALARM DO7 will not.

ALARM ENA Values.	
	ALARM ENA
0 default	No alarms are enabled.
1	Vent Alarm is enabled.
2	Alarm Switch is enabled.
4	Dif Alarm is enabled.

ALARM ENA Values.	
	ALARM ENA
5	Vent Alarm and Dif Alarm are enabled.
6	Alarm Switch and Dif Alarm are enabled.
7	Vent Alarm, Alarm Switch, and Dif Alarm are all enabled.



NOTE:

If ALARM ENA is set greater than 7, it will default to 0.

ALM ENA is additive. For example, if ALM ENA equals 5, then either a ventilation or a pressurization alarm will activate ALARM DO7, but the alarm switch will not.

ALARM DO7 is used to operate a local alarm annunciation device such as a light or horn in or near the room. Inputs can be set up to annunciate alarms from any combination of the following sources:

- Pressurization alarm point, VOL DIF ALM
(To connect VOL DIF ALM to DO 7, set ALM ENA to a value that enables the pressure alarm (4, 5, 6 or 7)).
- Ventilation alarm point, VENT ALM
(To connect VENT ALM to DO 7, set ALM ENA to a value that enables the ventilation alarm (1, 3, 5 or 7)).
- DI connected to a switch in the room, ALM SWIT DI6
(To connect ALM SWIT DI6 to DO 7, set ALM ENA to a value that enables the Alarm Switch (2, 3, 6 or 7)).
- Network alarm point, NET ALM CMD
(NET ALM CMD is always enabled for local annunciation.)

ALARM DO7 turns ON if any of the enabled alarm sources indicate an alarm. ALARM DO7 cannot be overridden.

NET ALM CMD can be commanded with the workstation software or PPCL to send an alarm state from the field panel. This makes it possible to program unique alarm criteria and annunciate alarms in specific rooms.

Network Annunciation

If the LCM is connected to a field panel, alarms can be reported using the workstation software, or by using a printer that is set up in a building manager's office to receive alarms. Points in the controller must be entered in the field panel's point database (referred to as unbundling) and defined as alarmable. For example, if the room pressurization alarm (VOL DIF ALM) is unbundled in a field panel and a pressurization alarm is triggered, an alarm will be annunciated across the network.

Damper Position on Return from Power Failure

On a return from power failure, the damper-command DOs (DOs1 through 4) remain OFF for 5 seconds prior to resuming control. Because of this it is recommended that the Supply Damper Motor Setup be set to Enabled (normally closed) for rooms where negative or neutral pressurization is required and Enabled and Reversed (normally open, where the actuator is retracted) for positively pressurized rooms. Likewise, it is recommended that the General Exhaust Damper Motor Setup be set to Enabled and

Reversed for rooms where negative or neutral pressurization is required and Enabled for positively pressurized rooms. The default for the Motor direction is direct (not reversed).

Use the values in the following table to determine the value for MTR SETUP. The values are additive. For example, if you want to have Motor 1 (DOs 1 and 2) enabled, Motor 2 (DOs 3 and 4) enabled and reversed, you would set MTR SETUP equal to 13. (This is because the Motor 1 enable value is 1, the Motor 2 enabled and reversed value is 12, $1+12=13$.)

	Not Used	Enabled	Enabled and Reversed
Motor 1 (supply damper) (DO 1 and DO 2)	0	1	3
Motor 2 (exhaust damper) (DO 3 and DO 4)	0	4	12

Operation of AVS FAILMODE

AVS FAILMODE is an enumerated point that describes how the supply Damper and the general exhaust Damper will respond if one or both Air Velocity Sensors (AVS) fail. It can handle both positively pressurized rooms and negatively pressurized rooms.

The default value of AVS FAILMODE is 0. This default causes both the supply and general exhaust to hold their current position when an AVS fails. Open Supply, Open Exhaust and Close Supply, Close Exhaust are not defined AVS FAILMODE states.

AVS Failure and AVS FAILMODE Table Values.	
	AVS FAILMODE
0 (default)	Hold Supply, Hold General Exhaust
1	Hold Supply, Open General Exhaust
2	Hold Supply, Close General Exhaust
3	Open Supply, Hold General Exhaust
4	Close Supply, Hold General Exhaust
5	Close Supply, Open General Exhaust
6	Open Supply, Close General Exhaust
7	VENTILATION
8	PRESSURE

AVS FAILMODE values are not additive. For example, if AVS FAILMODE equals 3, this means to open the supply Damper and hold the general exhaust Damper if an AVS fails.

The first seven values of AVS FAILMODE (0 through 6) describe specific actions taken when an AVS fails. For example, if AVS FAILMODE equals 5, then whenever an AVS fails, the supply Damper will always close and the general exhaust Damper will always open.

The last two values of AVS FAILMODE do not describe specific actions; that is, when an AVS fails, the supply and general exhaust will react differently depending on the circumstances.

If AVS FAILMODE equals 7, the supply Damper will hold. The general exhaust Damper will also hold if a fume hood is present (that is, if MAX HOOD VOL > 0). If a fume hood is absent, then the general exhaust Damper will close if the room is being positively pressurized and open if the room is neutral or negatively pressurized (that is if VOL DIF STPT is equal to or greater than 0).

If AVS FAILMODE equals 8, the supply Damper will open if the room is being positively pressurized and close if the room is neutral or negatively pressurized. The general exhaust Damper will hold if a fume hood is present. If a fume hood is absent, the general exhaust Damper will close if the room is being positively pressurized and open if the room is neutral or negatively pressurized.

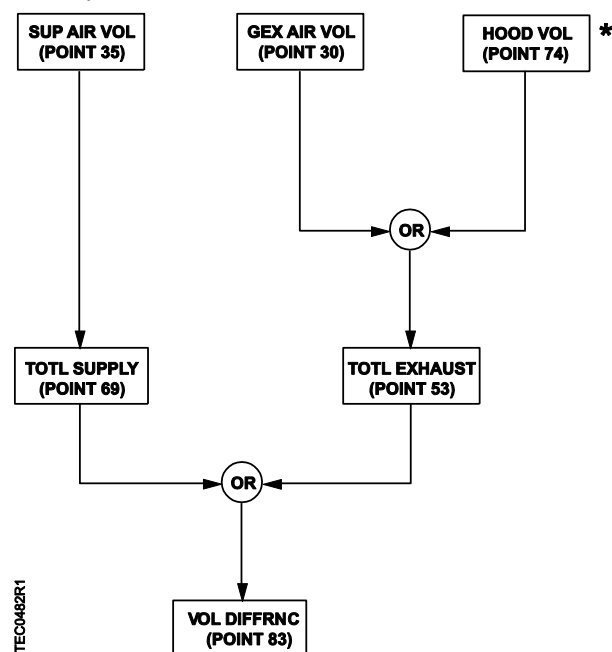


NOTE:

If AVS FAILMODE is set greater than 8, it will default to 0.

Fail Mode Operation

If one of the controller's accessories (inputs) fails, a failure mode sequence is initiated that leads to the failure of VOL DIFFRNC. The following figure shows the order in which points will fail.



* If MAX HOOD VOL is set to 0, a "Failed" status of HOOD VOL will not initiate a failure in TOTL EXHAUST or VOL DIFFRNC. See *Fume Hood Flow Input*.

Air Velocity Sensors – If one or both of the LCM air sensor signals (SUP AIR VOL, GEX AIR VOL) are out of range (for example, improper wiring to/from the Offboard Air Module(s), tubing not connected or connected backward), then the actions of the supply and general exhaust Dampers will depend on the value of AVS FAILMODE. Once GEX AIR VOL and SUP AIR VOL are normal, the supply and general exhaust Dampers return to normal operation.

See *Operation of AVS FAILMODE* for more information.

Fume Hood Flow – If the LCM receives an invalid (less than 1 Vdc) fume hood flow signal, or the fume hood controller (FHC) loses power or loses its flow sensor, HOOD VOL will fail. If HOOD VOL fails and if VOL DIF STPT is greater than or equal to 0 (negative or neutral pressurization required), the supply and exhaust loops assume a hood exhaust value of 0 cfm and continue to maintain user-defined pressurization. If HOOD VOL fails and VOL DIF STPT is less than 0 (positive pressurization required), the supply and exhaust loops assume the hood's exhaust value is equal to MAX HOOD VOL and continue to maintain user-defined pressurization. When the LCM is being used with fume hoods, and MAX HOOD VOL is set above its default of 0 cfm, a failure of HOOD VOL causes TOTL EXHAUST and VOL DIFFRNC to fail in succession (see figure). When VOL DIFFRNC fails, the pressurization alarm point, VOL DIF ALM, turns on automatically. If any of these points have been defined as alarmable and unbundled at the field panel, an alarm will be annunciated across the network.

**NOTE:**

If desired, the LCM can be used without any fume hoods attached. In this case, MAX HOOD VOL should be set to 0 cfm to disable the alarming that would occur if the fume hood flow input drops below 1 Vdc.

Laboratory Room Controller – If the LCM power fails, all actuators default to their user-defined fail-safe states. Since there is no power to the controller, no LEDs are available.

Electronic Actuator – If the actuator fails, typically, flow control is lost and alarms are triggered.

Upon loss of power or control signal to the actuator, it will move to its fail-safe position.

Room Temperature Sensor – If the room temperature sensor fails while CTL TEMP is not overridden or is not being adjusted by a field panel, then ROOM TEMP and CTL TEMP both display as “Failed” and temperature control is suspended at the current value of TEMP LOOPOUT. If ROOM TEMP is unbundled in a field panel and defined as alarmable, an alarm will be annunciated across the network.

If the room temperature sensor fails while CTL TEMP is overridden or is being adjusted by a field panel, then ROOM TEMP displays as “Failed”. CTL TEMP will continue to be overridden or adjusted by the field panel and room temperature control proceeds as normal. CTL TEMP will continue to have a status of NORMAL. If ROOM TEMP is unbundled in a field panel and defined as alarmable, an alarm will be annunciated across the network.

Room Temperature Setpoint Dial – If the room temperature setpoint dial fails while CTL STPT is not overridden or is not being adjusted by a field panel, then ROOM STPT and CTL STPT both display as “Failed” and the last known good value of ROOM STPT is used to determine the current value of CTL STPT. The rest of the room temperature PID loop is unaffected by the setpoint dial failure. If ROOM STPT is unbundled in a field panel and defined as alarmable, an alarm will be annunciated across the network.

If the room temperature sensor fails while CTL STPT is overridden or is being adjusted by a field panel, then ROOM STPT displays as “Failed”. CTL STPT will continue to be overridden or adjusted by the field panel and room temperature control proceeds as normal. CTL STPT will continue to have a status of NORMAL. If ROOM STPT is unbundled in a field panel and defined as alarmable, an alarm will be annunciated across the network.

Application Notes

Supply Only - Operating Without a General Exhaust Box

This application can operate without a general exhaust box. If a general exhaust box is not being controlled, set TRACK METHOD to FLOW and set the following points:

- TRACK MODE to 3.
 - Without a fume hood attached, use a value of 3 = ETS (exhaust tracks supply) Flow Tracking, should be used for both the occupied and unoccupied modes.
 - With a fume hood attached, use a value of 0 = STE (supply tracks exhaust) Flow Tracking, should be used for both the occupied and unoccupied modes.
- GEX FLO COEF to 0.
When GEX FLO COEF equals 0, GEX AIR VOL will always read 0, but will never display as Failed.
- OCC GEX MIN and UOC GEX MIN to 0.
If these two points are not set to 0, GEX AIR VOL— will read 0 since GEX FLO COEF was set to 0—will be less than the general exhaust box minimum, resulting in a false ventilation alarm.
- OCC GEX MAX and UOC GEX MAX left at default or a higher value.
These two points should be set to the highest value: 1) default or 2) OCC SUP MAX / UOC SUP MAX – small values will result in the supply box not being able to reach higher flow setpoints.

The application varies the supply airflow as the fume hood flow changes, in order to maintain the proper room pressurization. The supply airflow is not varied for cooling purposes; all temperature control is done by the reheat valve.

Because of this, START should be set to 100 to allow the reheat valve to be controlled by the full range of TEMP LOOPOUT and to prevent the room temperature PID Loop from winding up.

General Exhaust Only - Operating Without a Supply Box

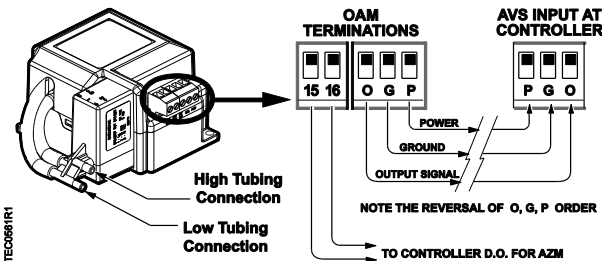
This application can operate without a supply box. If a supply box is not being controlled, set TRACK METHOD to FLOW and set the following points:

- TRACK MODE to 0.
A value of 0 = STE (supply tracks exhaust) Flow Tracking, should be used for both the occupied and unoccupied modes.
- SUP FLO COEF to 0.
When SUP FLO COEF equals 0, SUP AIR VOL will always read 0, but will never display as Failed.
- OCC SUP MIN and UOC SUP MIN to 0.
If these two points are not set to 0, SUP AIR VOL— will read 0 since SUP FLO COEF was set to 0—will be less than the supply box minimum, resulting in a false ventilation alarm.
- OCC SUP MAX and UOC SUP MAX left at default or a higher value.
These two points should be set to the highest value: 1) default or 2) OCC GEX MAX / UOC GEX MAX – small values will result in the exhaust box not being able to reach higher flow setpoints.

This setup is useful when the room has a constant source of supply air from other equipment or sources not connected to the controller. If you enter this constant supply air volume value into OTHER SUP, the application will vary the general exhaust airflow as the fume hood flow changes, in order to maintain the proper room pressurization.

Since all temperature control will be done by the reheat valve, START should be set to 100 to allow the reheat valve to be controlled by the full range of TEMP LOOPOUT and to prevent the room temperature PID Loop from winding up.

Wiring Diagrams



Offboard Air Module Wiring.



CAUTION

The LCM-OAVS has two terminal blocks with terminations numbered identically (terminations 1 through 16). **DO NOT** mix these up with each other.

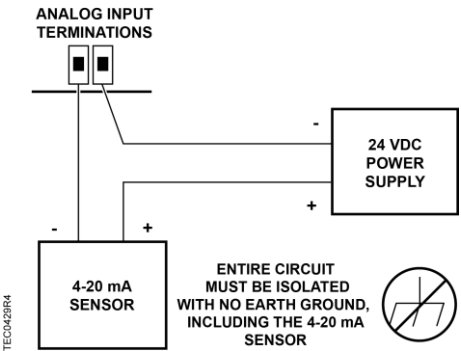
If the LCM-OAVS is not connected as shown, it is not resistant to electrical surges. It is also susceptible to interference from other equipment.



CAUTION

A separate power supply is required if a 4-20 mA sensor is used.

Failure to follow wiring precautions will result in equipment damage.



Wiring for AI with a 4 to 20 mA Sensor.



CAUTION

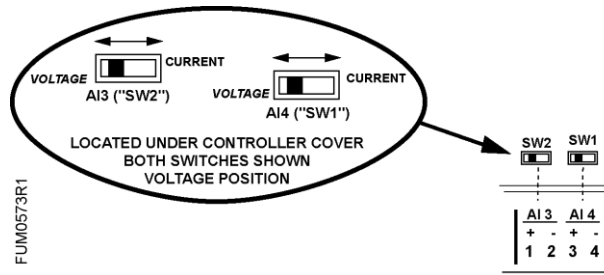
Each 4-20 mA sensor requires a SEPARATE dedicated power limited 24 Vdc power supply.

DO NOT use the same transformer to power both the sensor and the controller.



NOTE:

If the voltage/current switch is set to current and a 4 to 20 mA sensor is connected to an AI, then special wiring requirements must be followed.



NOTE:

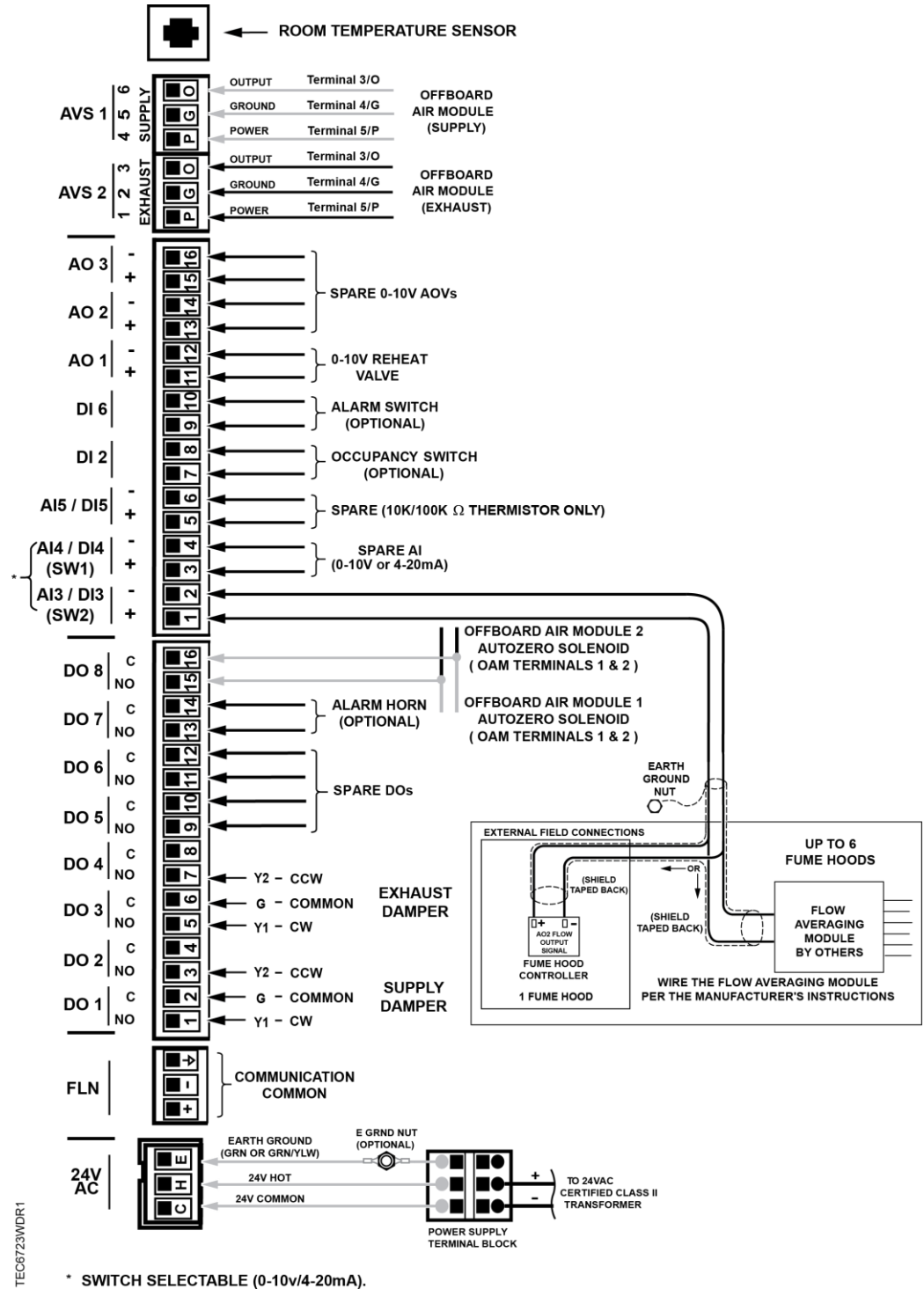
The controller's DOs control 24 Vac loads only. The maximum rating is 12 VA for each DO. An external interposing relay is required for any of the following:

- VA requirements higher than the maximum
- 110 or 220 Vac requirements
- DC power requirements
- Separate transformers used to power the load
(for example, part number 540-147, Terminal Equipment Controller Relay Module)



NOTE:

Thermistor inputs are 10K (default) or 100K software selectable (AI X).



TEC6723WDR1

BACnet LCM-OAVS Slow Actuation Damper Supply/Damper Exhaust – Application 6753 Wiring Diagram.

Point Database Application 6753

Object Type	Object Instance (Point Number)	Object Name (Descriptor)	Factory Default (SI Units)	Eng Units (SI Units)	Range	Active Text	Inactive Text
AO	1	CTLR ADDRESS	255	--	0-255	--	--
AO	2	APPLICATION	6792	--	0-32767	--	--
AO	3	TEMP OFFSET	0.0 (0.0)	DEG F (DEG C)	-31.75-32	--	--
AI	{04}	ROOM TEMP	74.0 (23.44888)	DEG F (DEG C)	48-111.75	--	--
AO	5	OCC DIF STPT	400 (188.7599)	CFM (LPS)	-8000-8380	--	--
AO	6	UOC DIF STPT	400 (188.7599)	CFM (LPS)	-8000-8380	--	--
AO	7	RM STPT MIN	55.0 (12.80888)	DEG F (DEG C)	48-111.75	--	--
AO	8	RM STPT MAX	90.0 (32.40888)	DEG F (DEG C)	48-111.75	--	--
AO	{09}	TEMP CTL VOL	0 (0.0)	CFM (LPS)	0-32764	--	--
AO	12	OCC ENA	0	--	0-255	--	--
AI	{13}	ROOM STPT	74.0 (23.44888)	DEG F (DEG C)	48-111.75	--	--
AI	{14}	AI 4	0	PCT	0-102.3	--	--
AI	{15}	HOOD SIG AI3	0	VOLTS	0-10.23	--	--
AO	16	VENT ALM DEL	30	SEC	0-255	--	--
AO	17	ALARM ENA	0	--	0-255	--	--
AO	18	START	50	PCT	0-102	--	--
BI	{19}	OCC BUTTON	OFF	--	Binary	ON	OFF
BO	{21}	OCC.UNOCC	OCC	--	Binary	UNOCC	OCC
BO	{22}	VOL DIF ALM	OFF	--	Binary	ON	OFF
BO	{23}	NET ALM CMD	OFF	--	Binary	ON	OFF
BI	{24}	OCC SWIT DI2	OFF	--	Binary	ON	OFF
BO	{25}	BUTTON CMD	OCC	--	Binary	UNOCC	OCC
AO	26	GEX P GAIN	0.015	--	0-4.095	--	--
BI	{27}	ALM SWIT DI6	OFF	--	Binary	ON	OFF
AO	28	TRACK MODE	0	--	0-255	--	--
BO	{29}	NET OCC CMD	OCC	--	Binary	UNOCC	OCC
AI	{30}	GEX AIR VOL	0 (0.0)	CFM (LPS)	0-32764	--	--
AO	{31}	OCC SUP MAX	3400 (1604.46)	CFM (LPS)	0-32764	--	--

Object Type	Object Instance (Point Number)	Object Name (Descriptor)	Factory Default (SI Units)	Eng Units (SI Units)	Range	Active Text	Inactive Text
AO	{32}	OCC SUP MIN	340 (160.446)	CFM (LPS)	0-32764	--	--
AO	{33}	OCC GEX MAX	1100 (519.09)	CFM (LPS)	0-32764	--	--
AO	{34}	OCC GEX MIN	600 (283.14)	CFM (LPS)	0-32764	--	--
AI	{35}	SUP AIR VOL	0 (0.0)	CFM (LPS)	0-32764	--	--
AO	36	SUP FLO COEF	0.73	--	0-2.55	--	--
AO	{37}	REHEAT AO1	0	VOLTS	0-10.23	--	--
AO	38	DIF ALM DBD	100 (47.19)	CFM (LPS)	0-4092	--	--
AO	39	DIF ALM DEL	30	SEC	0-255	--	--
AO	40	AVS FAILMODE	0	--	0-255	--	--
BO	{41}	DO 1	OFF	--	Binary	ON	OFF
BO	{42}	DO 2	OFF	--	Binary	ON	OFF
BO	{43}	DO 3	OFF	--	Binary	ON	OFF
BO	{44}	DO 4	OFF	--	Binary	ON	OFF
BO	45	TRACK METHOD	FLOW	--	Binary	FLOW	STPT
BO	{46}	DO 5	OFF	--	Binary	ON	OFF
BO	{47}	ALARM DO7	OFF	--	Binary	ON	OFF
BO	{48}	AUTOZERO DO8	OFF	--	Binary	ON	OFF
AO	{49}	VALVE CMD	0	PCT	0-102	--	--
AO	{50}	GEX DMP CMD	0	PCT	0-102	--	--
AO	52	MAX HOOD VOL	0 (0.0)	CFM (LPS)	0-32764	--	--
AI	{53}	TOTL EXHAUST	0 (0.0)	CFM (LPS)	0-32764	--	--
AO	54	GEX FLO COEF	0.73	--	0-2.55	--	--
AO	{55}	AO2	0	VOLTS	0-10.23	--	--
AO	{56}	AO3	0	VOLTS	0-10.23	--	--
AO	57	VALVE CLOSED	10	VOLTS	0-10.23	--	--
AO	58	VALVE OPEN	0	VOLTS	0-10.23	--	--
AO	60	GEXDUCT AREA	1.0 (0.09292)	SQ. FT (SQ M)	0-6.375	--	--
AO	{61}	OTHER SUP	0 (0.0)	CFM (LPS)	0-16380	--	--
AO	{62}	SUP DMP CMD	0	PCT	0-102	--	--
AO	65	ROOM P GAIN	20.0 (36.0)	--	0-8191.75	--	--
AO	66	ROOM I GAIN	0.01 (0.018)	--	0-32.767	--	--
AO	{67}	UOC GEX MAX	1000 (471.9)	CFM (LPS)	0-32764	--	--
AO	{68}	UOC GEX MIN	500	CFM (LPS)	0-32764	--	--

Object Type	Object Instance (Point Number)	Object Name (Descriptor)	Factory Default (SI Units)	Eng Units (SI Units)	Range	Active Text	Inactive Text
			(235.95)				
AI	{69}	TOTL SUPPLY	0 (0.0)	CFM (LPS)	0-32764	--	--
AO	70	SUP P GAIN	0.015	--	0-4.095	--	--
AO	{71}	UOC SUP MAX	2200 (1038.18)	CFM (LPS)	0-32764	--	--
AO	{72}	UOC SUP MIN	220 (103.818)	CFM (LPS)	0-32764	--	--
AO	{73}	CTL STPT	74.0 (23.44888)	DEG F (DEG C)	48-111.75	--	--
AI	{74}	HOOD VOL	0 (0.0)	CFM (LPS)	0-32764	--	--
AO	76	VOLUME STATE	1	--	0-255	--	--
BO	{77}	DO 6	OFF	--	Binary	ON	OFF
AO	{78}	CTL TEMP	74.0 (23.44888)	DEG F (DEG C)	48-111.75	--	--
AO	{79}	TEMP LOOPOUT	400	PCT	0-818.8	--	--
AI	{83}	VOL DIFFRNC	0 (-0.0001)	CFM (LPS)	-8000-8380	--	--
AI	{84}	AI 5	74.0 (23.496)	DEG F (DEG C)	37.5-165	--	--
AO	{85}	GEX FLO STPT	0 (0.0)	CFM (LPS)	0-16380	--	--
AO	86	FAIL LIMIT	40 (18.876)	CFM (LPS)	0-32764	--	--
AO	{88}	VOL DIF STPT	400 (188.7599)	CFM (LPS)	-8000-8380	--	--
AO	{89}	OTHER EXH	0 (0.0)	CFM (LPS)	0-16380	--	--
AO	90	OC V ALM LVL	0 (0.0)	CFM (LPS)	0-32764	--	--
AO	91	UC V ALM LVL	0 (0.0)	CFM (LPS)	0-32764	--	--
BO	{92}	VENT ALM	OFF	--	Binary	ON	OFF
AO	{93}	SUP FLO STPT	0 (0.0)	CFM (LPS)	0-16380	--	--
BO	{94}	CAL AIR	NO	--	Binary	YES	NO
AO	95	CAL SETUP	4	--	0-255	--	--
AO	96	CAL TIMER	12	HRS	0-255	--	--
AO	97	SUPDUCT AREA	1.0 (0.09292)	SQ. FT (SQ M)	0-6.375	--	--
AO	98	LOOP TIME	5	SEC	0-255	--	--
AO	{99}	ERROR STATUS	0	--	0-255	--	--
AO	104	SENSOR SEL	0	--	0-255	--	--
AO	106	MODHTG FLO	300 (1.524)	FPM (MPS)	0-4095	--	--
AO	107	DO DIR.REV	0	--	0-255	--	--
AI	{108}	RM RH	50	PCT	0-102	--	--
AO	109	FAIL TIME	60	SEC	0-510	--	--

Object Type	Object Instance (Point Number)	Object Name (Descriptor)	Factory Default (SI Units)	Eng Units (SI Units)	Range	Active Text	Inactive Text
AO	110	MTR SETUP	0	--	0-255	--	--
AO	{111}	SUP DMP POS	0	PCT	0-102	--	--
AO	112	MTR1 TIMING	95	SEC	0-511	--	--
AO	113	MTR1 ROT ANG	90	--	0-255	--	--
AO	{114}	GEX DMP POS	0	PCT	0-102	--	--
AO	115	MTR2 TIMING	95	SEC	0-511	--	--
AO	116	MTR2 ROT ANG	90	--	0-255	--	--
AO	117	MINHOODVOLTS	1	VOLTS	0-10.23	--	--
AI	{118}	RM CO2	1000	PPM	0-8191	--	--
AO	125	SUP MAX RATE	0 (0.0)	FPM (MPS)	0-4095	--	--
AO	126	GEX MAX RATE	0 (0.0)	FPM (MPS)	0-4095	--	--
BO	{127}	PPCL STATE	EMPTY	--	Binary	LOADED	EMPTY

1) Object Types are: Analog Input (AI), Analog Output (AO), Binary Input (BI) and Binary Output (BO).

2) A single value in a column means that the value is the same in English units and in SI units.

3) Point numbers that appear in brackets { } may be unbundled at the field panel.

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Object Type	Object Instance (Point Number)	Object Name (Descriptor)	Factory Default (SI Units)	Eng Units (SI Units)	Range	Active Text	Inactive Text
AO	1	CTLR ADDRESS	255	--	0-255	--	--
AO	2	APPLICATION	6792	--	0-32767	--	--
AO	3	TEMP OFFSET	0.0 (0.0)	DEG F (DEG C)	-31.75-32	--	--
AI	{04}	ROOM TEMP	74.0 (23.44888)	DEG F (DEG C)	48-111.75	--	--
AI	{13}	ROOM STPT	74.0 (23.44888)	DEG F (DEG C)	48-111.75	--	--
AI	{14}	AI 4	0	PCT	0-102.3	--	--
AI	{15}	AI 3	0	VOLTS	0-10.23	--	--
BI	{19}	OCC BUTTON	OFF	--	Binary	ON	OFF
BO	{21}	OCC.UNOCC	OCC	--	Binary	UNOCC	OCC
BO	{23}	NET ALM CMD	OFF	--	Binary	ON	OFF
BI	{24}	DI 2	OFF	--	Binary	ON	OFF
BO	{25}	BUTTON CMD	OCC	--	Binary	UNOCC	OCC
BI	{27}	DI 6	OFF	--	Binary	ON	OFF
AI	{30}	AIR VOLUME 2	0 (0.0)	CFM (LPS)	0-32764	--	--
AI	{35}	AIR VOLUME 1	0 (0.0)	CFM (LPS)	0-32764	--	--
AO	36	FLOW COEF 1	0.73	--	0-2.55	--	--
AO	{37}	AO1	0	VOLTS	0-10.23	--	--
BO	{41}	DO 1	OFF	--	Binary	ON	OFF
BO	{42}	DO 2	OFF	--	Binary	ON	OFF
BO	{43}	DO 3	OFF	--	Binary	ON	OFF
BO	{44}	DO 4	OFF	--	Binary	ON	OFF
BO	{46}	DO 5	OFF	--	Binary	ON	OFF
BO	{47}	DO 7	OFF	--	Binary	ON	OFF
BO	{48}	DO 8	OFF	--	Binary	ON	OFF
AO	54	FLOW COEF 2	0.73	--	0-2.55	--	--
AO	{55}	AO2	0	VOLTS	0-10.23	--	--
AO	{56}	AO3	0	VOLTS	0-10.23	--	--
AO	60	DUCT AREA 2	1.0 (0.09292)	SQ. FT (SQ M)	0-6.375	--	--
BO	{77}	DO 6	OFF	--	Binary	ON	OFF
AO	{78}	CTL TEMP	74.0 (23.44888)	DEG F (DEG C)	48-111.75	--	--

Object Type	Object Instance (Point Number)	Object Name (Descriptor)	Factory Default (SI Units)	Eng Units (SI Units)	Range	Active Text	Inactive Text
AI	{84}	AI 5	74.0 (23.496)	DEG F (DEG C)	37.5-165	--	--
BO	{94}	CAL AIR	NO	--	Binary	YES	NO
AO	95	CAL SETUP	4	--	0-255	--	--
AO	96	CAL TIMER	12	HRS	0-255	--	--
AO	97	DUCT AREA 1	1.0 (0.09292)	SQ. FT (SQ M)	0-6.375	--	--
AO	{99}	ERROR STATUS	0	--	0-255	--	--
AO	104	SENSOR SEL	0	--	0-255	--	--
AO	107	DO DIR.REV	0	--	0-255	--	--
AI	{108}	RM RH	50	PCT	0-102	--	--
AI	{118}	RM CO2	1000	PPM	0-8191	--	--
BO	{127}	PPCL STATE	EMPTY	--	Binary	LOADED	EMPTY

- ¹⁾ Object Types are; Analog Input (AI), Analog Output (AO), Binary Input (BI) and Binary Output (BO).
- ²⁾ A single value in a column means that the value is the same in English units and in SI units.
- ³⁾ Point numbers that appear in brackets { } may be unbundled at the field panel.

Issued by
Siemens Industry, Inc.
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